

Multifunctional damper actuator for adjusting air dampers in ventilation and air conditioning systems in buildings

- Air damper size up to approx. 8 m²
- Torque 40 Nm
- Nominal voltage AC/DC 24 V
- Control: Modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- · Communication via BELIMO MP-Bus
- · Conversion of sensor signals



Technical data				
Electrical data				
Nominal voltage	AC 24 V, 50/60 Hz / DC 24 V			
Power supply range	AC 19.2 28.8 V / DC 21.6 28.8 V			
Power consumption in operation At rest For wire sizing	4.5 W at nominal torque 1.5 W 7 VA			
Connection	Cable 1 m, 4 x 0.75 mm ²			
Functional data	Factory settings	Variable Setting		
Torque (nominal torque)	Min. 40 Nm at nominal voltage	25%, 50%, 75% reduced		
Control Control signal Y	DC 0 10 V, input impedance 100 kΩ	Open-close, 3-point (AC only)		
Working range	DC 2 10 V	Start point DC 0.5 30 V End point DC 2.5 32 V		
Position feedback (measuring voltage U)	DC 2 10 V, max. 0.5 mA	Start point DC 0.5 8 V End point DC 2.5 10 V		
Uni-rotation	±5%			
Direction of rotation	Can be selected with 0 / 1			
Direction of motion at Y = 0 V	In switch position 0 🗸 or 1 🦳 Electronically reversible			
Manual override	Disengaging the gearing latch by means of a pushbutton, self-resetting			
Angle of rotation	Max. 95°			
Running time	150 s	75 290 s		
Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation	Manual triggering of this adaption by pressing the button «Adaption» or with the PC-Tool	Automatic adaption whenever the supply voltage is switched on, or manual triggering		
Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, only AC) = 50%	% MAX = (MIN + 30°<) 100% % MIN = 0% (MAX – 30°<)		
Sound power level	Max. 45 dB (A) With a running 75 s = 50 dB (A) time of 290 s < 40 dB (A)			
Position indication	Mechanical, plug-on			
Safety				
Protection class	III Safety extra-low voltage			
Degree of protection	IP54 in all mounting positions			
EMC	CE according to 89/336/EEC			
Mode of operation	Type 1 (to EN 60730-1)			
Rated impulse voltage	0.8 kV (to EN 60730-1)			
Control pollution degree	3 (in acc. with EN 60730-1)			
Ambient temperature range	−30 +50°C			
Non-operating temperature	−40 +80°C			
Ambient humidity range	95% r.H., non-condensating (to EN 60730-1)		
Maintenance	Maintenance-free			



Technical data	(Continued)	
Dimensions/weight		
Dimensions	See «Dimensions» on page 5	
Weight	Approx. 1'730 g	

Safety notes



- The damper actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel.
 All applicable legal or institutional installation regulations must be complied with.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · The cable is not allowed to be removed from the unit.
- When calculating the torque required, the specifications supplied by the damper manufacturers concerning the cross section, design and installation site, and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

Conventional operation: The actuator is controlled with a standard modulating signal of DC 0 ... 10 V and travels to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0 ... 100% and as slave control signal for other actuators. Operation on the MP-Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and travels to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators

The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, MFT-P.

Simple direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

Manual override

Manual operation with self-resetting pushbutton possible (the gear is disengaged for as long as the button is pressed).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Home position

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement" switch, the actuator travels to the home position.

Pos. direction of rotation switch		Home position		
%	Y = 0 🚩	ccw 🚩	Left stop	
i	Y = 0	Cw	Right stop	

The actuator then moves into the position defined by the control signal.

Accessories		
	Description	Data sheet
Electrical accessories	Auxiliary switch SA	T2 - SA
	Feedback potentiometer PA	T2 - PA
	Manual parameterising device MFT-H	T2 - MFT-H
	PC-Tool MFT-P	T2 - MFT-P
	Position sensor SG24 (only in conventional mode)	T2 - SG24
	Digital position indication ZAD24 (only in conventional mode)	T2 - ZAD24
Mechanical accessories	Various accessories (clamps, shaft extensions etc.)	T2 - Z-GMA



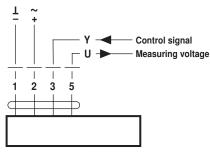
Electrical installation

Wiring diagram

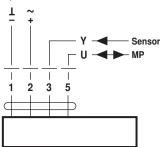
Note

- Connect via safety isolation transformer.
- Parallel connection of other actuators possible. Note the performance data.

Conventional operation

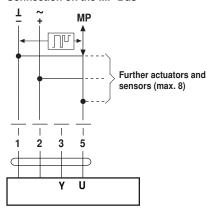


Operation on the MP-Bus



Functions when operated on MP-Bus

Connection on the MP-Bus



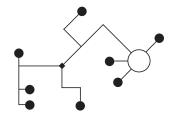
Supply and communication

in one and the same 3-wire cable

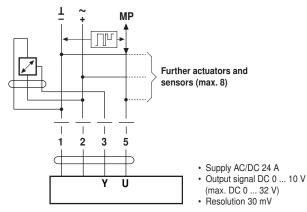
- no shielding or twisting necessary
- · no terminating resistors required

Power topology

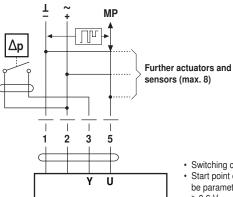
There are no restrictions for the network topology (star, ring, tree or hybrid forms are permitted).



Connection of active sensors

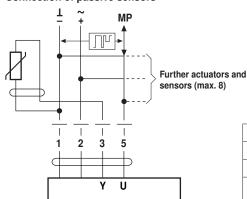


Connection of external switching contact



- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as ≥ 0.6 V

Connection of passive sensors

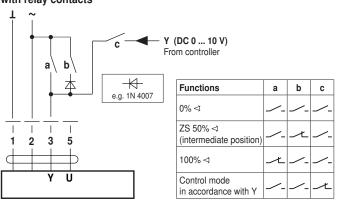


Sensor	Temperature range	Resistance range	Resolution
Ni1000	−28 +98°C	850 1600 Ω	1 Ω
PT1000	−35 +155°C	850 1600 Ω	1 Ω
NTC	-10 +160°C (depending on type)	200 Ω 60 kΩ	1 Ω

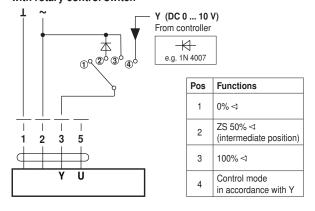


Functions with basic values (only in conventional mode)

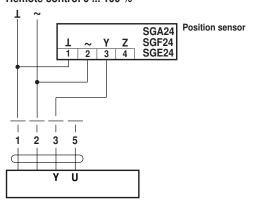
Override control with AC 24 V with relay contacts



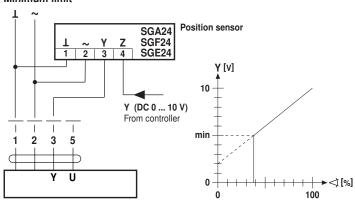
Override control with AC 24 V with rotary control switch



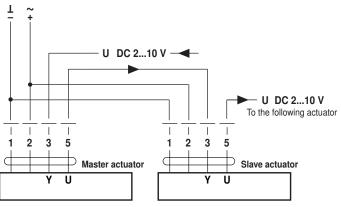
Remote control 0 ... 100 %



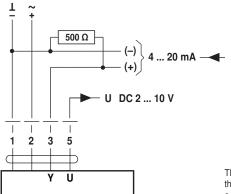
Minimum limit



Master/Slave control (position-dependent)

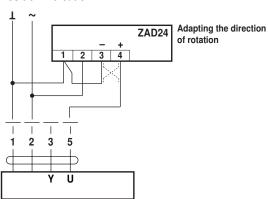


Control with 4 ... 20 mA via external resistance

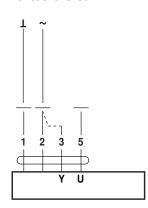


The 500 Ω resistor converts the 4 ... 20 mA current signal to a voltage signal DC 2 ... 10 V

Position indication



Functional check



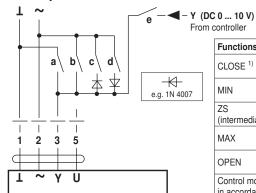
Procedure

- Apply AC 24 A to connection 1 and 2
- Disconnect connection 3:
- For direction of rotation 0:
 Actuator turns in the direction of *
- For direction of rotation 1:
- Actuator turns in the direction of Short circuit connections 2 and 3:
- Actuator runs in the opposite direction



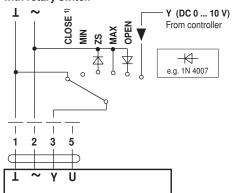
Functions for actuators with specific parameters

Override control and limiting with AC 24 V with relay contacts



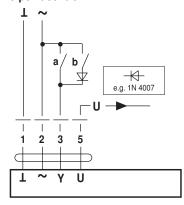
Functions	а	b	С	d	е
CLOSE 1)	1		<u> </u>	<u> </u>	
MIN	<u> </u>	<u></u> _	<u> </u>	/-	
ZS (intermediate position)	<u> </u>	/ _	1	/-	<u></u>
MAX		1		<u> </u>	
OPEN	<u> </u>	<u> </u>	<u> </u>	1	
Control mode in accordance with Y				<u></u>	1

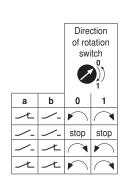
Override control and limiting with AC 24 V with rotary switch



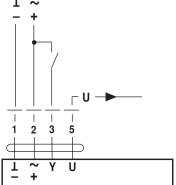
1) Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V.

3-point control



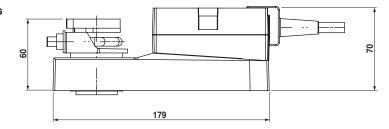


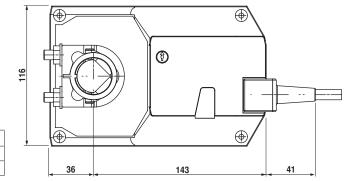
Open/close control



Dimensions [mm]

Dimensional diagrams





Damper spindle	Length	010
Clamp on top	Min. 52	14 26
Clamp on bottom	Min. 20	14 26



Operating controls and indicators



1) Direction of rotation switch

Switching over: Direction of rotation changes

2 Pushbutton and green LED display

Off: No voltage supply or malfunction

Green on: Operation

Press button: Switches on angle of rotation adaption followed by standard operation

3 Pushbutton and yellow LED display

Off: Standard operation without MP-Bus
Yellow on: Adaption or synchronising process active
Yellow, blinking: Addressing request sent to MP master
Press button: Acknowledgment of addressing
Yellow, flickering: MP communication active

(4) Gear disengagement switch

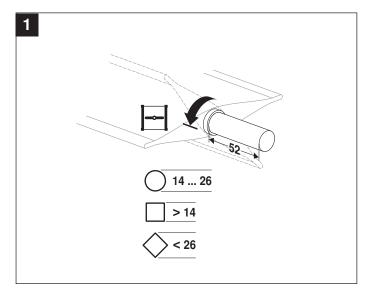
Press button: Gear disengaged, motor stops, manual operation possible

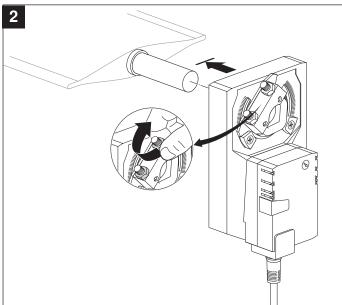
Release button: Gear engaged, synchronisation starts, followed by standard operation

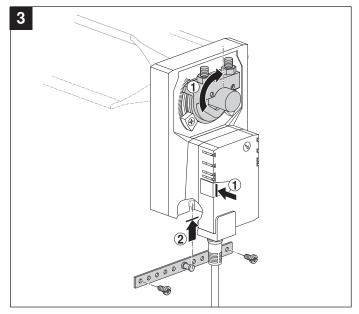
5 Service plug

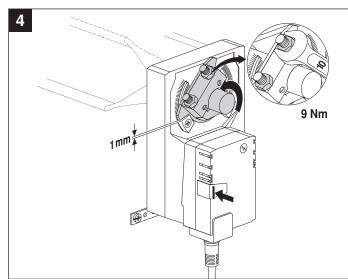
For connecting parameterising and service tools

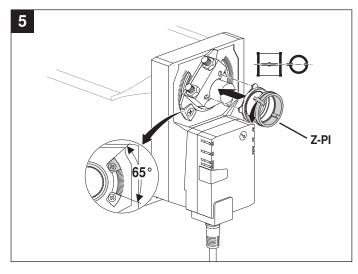


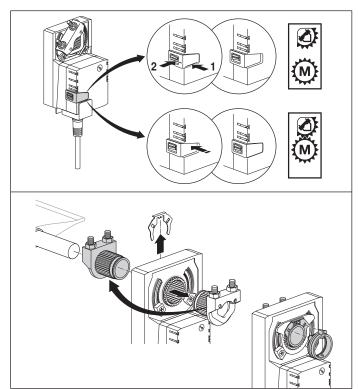






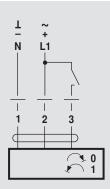


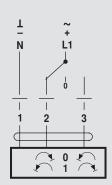






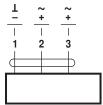






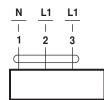


AC 24 V / DC 24 V



GM24A..

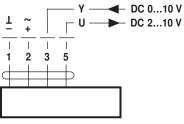
AC 100 ... 240 V



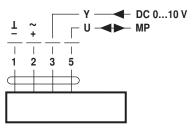
GM230A..



AC 24 V / DC 24 V



GM24A-SR.. GM24A-MF..



GM24A-MP..